

Fast Browsing of Archived Web Contents

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September 18, 2008

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Motivation and Goal

Web Graph



- Web as a weighted, directed graph.
 - Web page → Vertex
 - Hyperlink → Edge
 - Page size \rightarrow Vertex weight



Web Containers

- A multitude of web pages are aggregated into a container (e.g. WARC)
- Each container serves as an archive object
- Currently adopted by the Internet Archive, and many other national archives, and libraries





Current Container Packaging

- BFS or DFS based crawls
- First seen page → first put into a container
- When a container is full, a new container is is created.

Input Seed URLs : {url₁, url₂, ... } MAX SIZE Procedure 1: **Enqueue**(Q, Seed URLs) 2: $i \leftarrow 1$ 3: visited[] ← FALSE 4: C_i \leftarrow new **Container**() 5: while (Q is non-empty) $u \leftarrow Dequeue(Q)$ 6: Fetch(u); 7: visited[u] 🗲 TRUE 8: if $(Size(C_i) + Size(u) > MAX SIZE)$ 9: i = i + 110: $C_i = \text{new Container}()$ 11: $C_i = C_i \quad U \quad u$ 12: for each $v \in adjacent[u]$ 13: if (visited[u] = FALSE) 14: **Enqueue** (Q, V)15:



September 18, 2008

Our Goal



• Minimize the probability that a user jumps often between containers.



Packaging Issues



Main Issue: How to minimize the number of containers necessary when accessing the archived web pages?

> How to put together more relevant web pages in the same container? → Graph Partitioning

> > How to define `relevancy'? → Graph Analysis



Our Approach

Our Approach



- Graph Analysis
 - Web graph is analyzed to obtain, for each edge, a global probability that the edge is taken.
- Graph Partitioning
 - Using edge weights from graph analysis, find the best partition where the sum of edge weights across different parts is minimized, and the size of each part is balanced.

Input

```
Seed URLs : {url<sub>1</sub>, url<sub>2</sub>, ... }
MAX_SIZE
```

Procedure

- 1: G BuildWebGraph (Seed URLs)
- 2: n GetNumberOfContainers(G,MAX_SIZE)
- 3: G EdgeRank(G) /* Optional */
- 4: $\{UL_1, UL_2, ..., UL_n\} \leftarrow PartitionGraph(G, n)$
- 5: for ($1 \leq i \leq n$)
- 6: $C_i \leftarrow \text{new Container()}$
- 7: for $(v \in UL_n)$
 - fetch(v)
 - $C_i = C_i U V$

8:

9:

Graph Analysis (1/2)



- PageRank [Brin, S. and Page, L, 1998]
 - Computes the importance of each web page.
 - Pages linked from important pages are considered important.

- Ideal model:
$$PR(u) = \sum_{v \in I_u} p_{vu} PR(v)$$

- Two problems.
 - Dangling pages → Solution: artificial out-links to all the other pages from dangling pages, w/ probability of 1/N
 - Cyclic paths → Solution: artificial out-links to all the other pages from each page, w/ probability of 1-d

- Modified model:
$$PR(u) = \frac{1-d}{N} + d\sum_{v \in I_u} p_{vu} PR(v)$$



Graph Analysis (2/2)

• EdgeRank

$$ER(e) = \frac{PR(v)}{\text{outdegree}(v)}$$

• EdgeRank is used in our simulation

Graph Partitioning (1/2)



- Edge-Cut : The sum of the weights of the edges that connect any two different parts.
- Web Graph Partitioning Problem: Given a directed web graph G:(V, E) with weighted nodes (weight of a node is the size of the corresponding page) and weighted edges, determine a partition V = P₁ U P₂ U P₃ U ... U P_n such that,
 - 1. Edge-Cut is minimized.
 - 2. For all *i*'s, $|P_i| \le K$ for some fixed *K*, where $|P_i|$ is the sum of the weights of the vertices in P_i and *K* is an upper bound on the size of a container.
- This is an NP-Complete problem

Graph Partitioning (2/2)



- Scheme used in simulation: [Karypis and Kumar, 1998]
 - Fast multilevel graph partitioning algorithm
 - 1. First compute a maximal matching using a randomized algorithm
 - 2. Coarsen the graph by collapsing the matched vertices together
 - 3. Repeat 1~2 until a desired size of the coarsened graph is achieved
 - 4. Compute minimum edge-cut bisection
 - 5. Refine & uncoarsen the partitioned graph.



Experiments

Experiment Settings (1/2)



- Datasets
 - UMIACS : Web Graph built from our crawls of http://umiacs.umd.edu in 2007
 - Stanford : Web Graph built from a crawl of http://stanford.edu in 2002 by the Stanford WebBase project

• Dataset Properties

Datasets	# Vertices	# Edges	Total Vertex Weight
UMIACS Web Graph	4579	9732	2.49GB
Stanford Web Graph	281903	2312497	215.82GB

Experiment Settings (2/2)



- Three packaging methods
 - CONV: Pages are allocated to containers as they are fetched during the crawling process (BFS). Once a container is full, we use a new container.
 - GP: The graph partitioning technique is applied so as to minimize the number of edges connecting any two partitions. All the pages belonging to a partition are allocated to a single container.
 - ER+GP: EdgeRank is used to assign weights to edges, and the graph is partitioned using a minimum-weight partitioning algorithm.

Edge-Cut Result





Edge Cut	Unweighted Edges		Weighted Edges	
Euge-Cui	CONV	GP	ER+CONV	ER+GP
UMIACS Web Graph	73.87	12.38	62.36	36.03
Stanford Web Graph	80.50	47.33	63.56	32.20

Simulation



• Simulation Parameters

Parameter	Value
Number of Random Walks	1000
Number of Hops in Each Walk	10
Probability of Going Back	30%
Out-degree of Starting Vertex	> 5
Policy At Dangling Vertex	Go back



Simulation Results (UMIACS)



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Simulation Results (Stanford)



Simulation Results







Conclusion

Conclusion



- We have shown that a graph partitioning scheme for organizing archive containers significantly reduces the number of containers that need to be accessed when a user browses through the archived web material.
- A graph analysis technique can improve this number even further.
- The overhead required by this technique is relatively small. On our 2 Ghz Intel Core 2 Duo processor, we could fully partition and compute EdgeRank of a large graph (the Stanford web graph that contains about 300,000 vertices, and 2.3 million edges) within minutes.
- Our simulation considers random access pattern on a single version of pages. However, the Web Graph model, and graph analysis technique can be extended to accommodate other access patterns on multiple versions.